

Physical Applications of Geometric Algebra

Formula Sheet

Geometric Product

$$ab = a \cdot b + a \wedge b$$

$$ba = a \cdot b - a \wedge b$$

$$a \cdot A_r = \frac{1}{2}(aA_r - (-1)^r A_r a)$$

$$a \wedge A_r = \frac{1}{2}(aA_r + (-1)^r A_r a)$$

Multivectors

$$A = \langle A \rangle_0 + \langle A \rangle_1 + \cdots = \sum_r \langle A \rangle_r$$

$$A_r B_s = \langle A_r B_s \rangle_{|r-s|} + \langle A_r B_s \rangle_{|r-s|+2} + \cdots + \langle A_r B_s \rangle_{r+s}$$

$$A_r \cdot B_s = \langle A_r B_s \rangle_{|r-s|}$$

$$A_r \cdot \lambda = 0 \quad \text{for scalar } \lambda$$

$$A_r \wedge B_s = \langle A_r B_s \rangle_{r+s}$$

$$\langle AB \rangle = \langle BA \rangle$$

$$A_r \cdot (B_s \cdot C_t) = (A_r \wedge B_s) \cdot C_t \quad r + s \leq t \text{ and } r, s > 0$$

$$A_r \cdot (B_s \cdot C_t) = (A_r \cdot B_s) \cdot C_t \quad r + t \leq s$$

$$A \times (B \times C) + C \times (A \times B) + B \times (C \times A) = 0$$

Frequently Used. a, b, c, d vectors, B bivector.

$$a \cdot (b \wedge c) = a \cdot b \, c - a \cdot c \, b$$

$$(a \wedge b) \cdot (c \wedge d) = a \cdot d \, b \cdot c - a \cdot c \, b \cdot d$$

$$a \cdot (b \cdot B) = (a \wedge b) \cdot B$$

$$(a \wedge b) \times (c \wedge d) = b \cdot c \, a \wedge d - a \cdot c \, b \wedge d + a \cdot d \, b \wedge c - b \cdot d \, a \wedge c$$

$$(a \wedge b) \times B = (a \cdot B) \wedge b + a \wedge (b \cdot B)$$

Bivectors.

$$BC = B \cdot C + B \times C + B \wedge C$$

$$CB = B \cdot C - B \times C + B \wedge C$$

$$B \times A_r = \langle B \times A_r \rangle_r$$

$$B \times (MN) = B \times M \, N + M \, B \times N \quad \forall M, N$$

Pseudoscalar

$$\begin{aligned} A_r \cdot (B_s I) &= A_r \wedge B_s I & r + s &\leq n \\ A_r \wedge (B_s I) &= A_r \cdot B_s I & r &\leq s \end{aligned}$$

Reflections and Rotations

$$\begin{aligned} A_r &\mapsto (-1)^r n A_r n \\ A_r &\mapsto R A_r \tilde{R} \\ R &= e^{-B/2} = kl \cdots mn \\ R \tilde{R} &= \tilde{R} R = 1 \end{aligned}$$

Linear Algebra

$$\begin{aligned} \mathbf{f}(a \wedge b \wedge \cdots \wedge c) &= \mathbf{f}(a) \wedge \mathbf{f}(b) \wedge \cdots \wedge \mathbf{f}(c) \\ \mathbf{f}(I) &= \det(\mathbf{f}) I \\ \bar{\mathbf{f}}(b) &= e_k \mathbf{f}(e^k) \cdot b = \partial_a \mathbf{f}(a) \cdot b \\ \mathbf{f}(A_r) \cdot B_s &= \mathbf{f}[A_r \cdot \bar{\mathbf{f}}(B_s)] \quad r \geq s \\ A_r \cdot \bar{\mathbf{f}}(B_s) &= \bar{\mathbf{f}}[\mathbf{f}(A_r) \cdot B_s] \quad r \leq s \\ \mathbf{f}^{-1}(A) &= \det(\mathbf{f})^{-1} I \bar{\mathbf{f}}(I^{-1} A) \\ \bar{\mathbf{f}}^{-1}(A) &= \det(\mathbf{f})^{-1} I \mathbf{f}(I^{-1} A) \end{aligned}$$

Frames and contractions

$$\begin{aligned} e^i \cdot e_j &= \delta_j^i \\ e^k &= (-1)^{k+1} e_1 \wedge \cdots \wedge \check{e}_k \wedge \cdots \wedge e_n E_n^{-1} \\ E_n &= e_1 \wedge e_2 \wedge \cdots \wedge e_n \\ e_k e^k \cdot A_r &= \partial_a a \cdot A_r = r A_r \\ e_k e^k \wedge A_r &= \partial_a a \wedge A_r = (n - r) A_r \\ e_k A_r e^k &= \dot{\partial}_a A_r \dot{a} = (-1)^r (n - 2r) A_r \end{aligned}$$

Geometric Calculus

$$\begin{aligned} \nabla(AB) &= \nabla A B + \dot{\nabla} A \dot{B} \\ \nabla \wedge \nabla &= 0 \\ \nabla(x \cdot a) &= a \\ \nabla x^2 &= 2x \end{aligned}$$